NASA - Langley

X64-358.47

ROTARY-TYPE RECOVERY SYSTEMS by Charles E. Libbey

The Langley Research Center has tested, or is currently testing, several types of rotary devices with applications for recovery systems. The first slide is a chart of these systems showing the areas where data are presently available and the areas where research is still required.

(Slide.)

The vortex ring parachute resembles 3 Maltese cross when viewed from above. Deployment, stability, and performance tests have been completed. A report containing this data is in the review stage now and will be available soon. This system is not intended to glide, however as for most parachutes, it can be forced to produce a small amount of L/D.

The flexable rotary wing consists of strong cables at the leading and trailing edges with parachute type material stratched between them. A weight at the tip provides centrifugal force to maintain all components in tension while rotating. Some preliminary deployment tests have been conducted using a 4-bladed 6 foot diameter model. The cloth rotor blades were attached to a 32 inch diameter vortex ring parachute which were used to provide the initial rotation for the system. After the deployments, the rate of rotation increased, indicating that the blades were autorotating and were not being driven by the rotating parachute. Performance data have been obtained for a 2-bladed 4-foot diameter rotor, most of it for the vertical autorotative descent condition. For these tests, the blades were attached to a short wooden paddle wheel type of hub arrangement. A few tests at lower angles of attack have indicated that this system does have gliding capabilities although how weil it will glide is not known.

The conventional rotal wing is the helicopter type system. This is the configuration for which a vast amount of performance data are available, including data for gliding flight and flared landings. This is the configuration for which most of the tests on stability in vertical autorotation descent have been conducted. No deployment tests have been conducted, and none are planned.

The folding and the telescoping rotary wings are essentially the same as the conventional rotary wings, but they are intended for a more compact stowage of the system. Lap ownent tests are planned for both of those by team. The effects, if any, of the telescoping joints on the folding hinges on the performance is not known. A few stability tests have been conducted using 4 foot diameter models with telescoping and folding type construction. (Slide off.)

I would now like to discuss some of the areas of this chart for which data are available. A short film will be presented next which shows a vortex ring parachute being deployed while in free fall and notating.

(Film.)

As you have seen in the movie, the parachute is very stable with escillations of less than 1° . The next slide shows the variation of the coefficient of drag with the incedence setting of the individual blades (canopy segments). (Slide.) The drag coefficient is based on the total cloth area of the parachute. The high drag ($C_p=2.1$) obtained with this particular parachute would mean that for a given payload the rate of decort would only be 60 percent of what it would be if a conventional parachute of the same cloth area were used. (Slide off.)

A few preliminary deployment tests of flexable fabric blades have been conducted and have pointed our some of the problem areas which will

problem areas will be shown. This film was taken at approximately

1500 trames per second and will be projected at 24 frames per second.

Therefore, the motions seen are approximately 60 times shower than they actually recurred. The deployment of the blades cakes place in about one supproximately of a second. The steady state motion seen after the deployment, was taken approximately 6 seconds later. It is part of the same test.

(Film.) It is believed that the problem illustrated in this film can be solved with a controlled state deployment of the blades.

Experience in the Recovery Systems Branch has indicated that use of a rotary wing recovery system may involve problems of dynamic stability. Parametric tests are being conducted at Langley to determine how much affect the various parameters have on the stability of a sotary wing in free vertical autorotation descent. Some of the parameters which have been very briefly examined and have been shown to have an effect on the stability of this system are listed in the following side. (Clide.)

There are other variables which quite likely effect the stability also, such as, solidity ratio, number of blades, blade weight, blade incidence angle, and payload configuration.

The next film will illustrate a rigid rotary wing on an apollo type capsule in vertical autorotative descent. The first sequence is an unstable configuration. By varying one of the parameters (in this case hub inertia), the stability was increased as seen in the second sequence, however, it was still only many hally stable. A further modefication produced a completely stable configuration. (Film.)

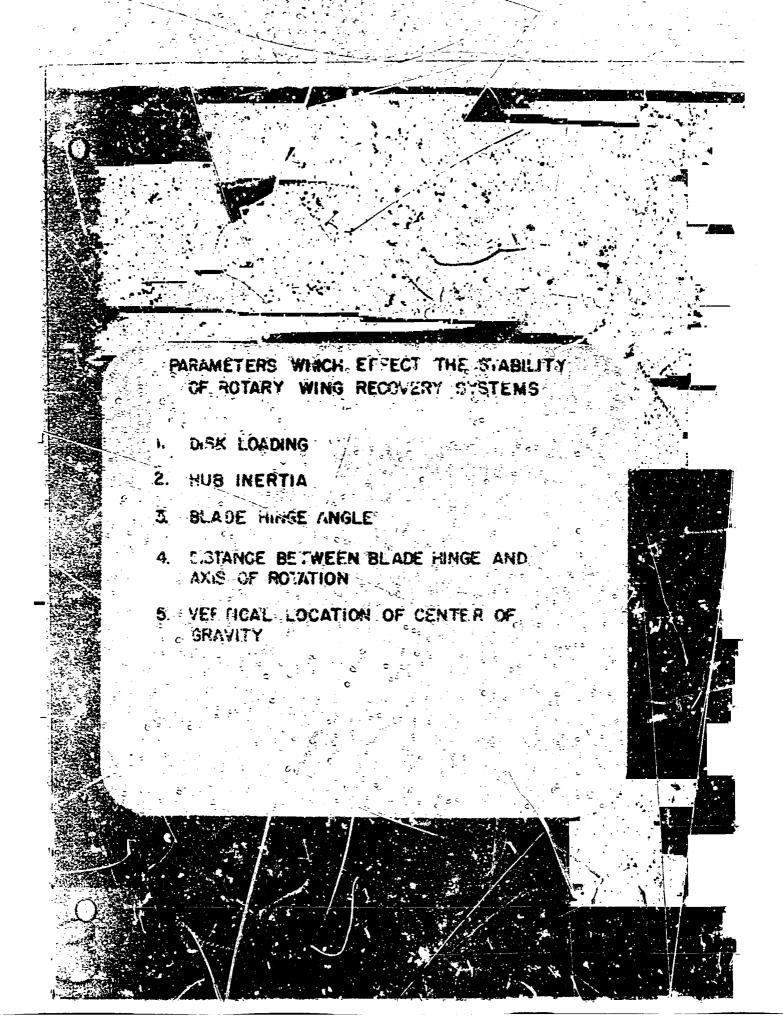
. few tests have been conducted with a 49 inch diameter rotar, considering only two variables, bub inercia and disk loading. The results are presented in the next slide. (Slide.)

the disk loading must also be increased to maintain stability. !! some of the other parameters are changed, this curve will be shifted. For instance, decreasing the blade hinge and will shire the curve downward.

In conclusion, it can be said that retary type recovery systems can be made inherantly stable, can produce high drap, fair gliving capability, and near zero vertical and horizontal speeds at landing.

DEPLOYMENT STABILITY PERFORMANCE SOME DATA AVAILABLE ROTARY-TYPE RECOVERY SYSTEMS SOME SOME YES CONVENTIONAL ROTARY WING TELESCOPING ROTARY WINC CORTEX PING PARACHUTE FLEXIBLE ROTARY WING FOLDING ROTARY WING

VARIATION OF CD WITH BLADE PITCH SETTING FOR 64" DIA VORTEX RING PARACHUICE iS 12 2 BLADE TIP PITCH SETTING



2000 REGION 1000 STABLE REGION DISK LOADING, LBS/FT2